Learning Algebraic Functions From a Few Samples

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Based on joint works with Amir Shpilka

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$$f(x,y) := x/y$$



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Examples:



$$f(x,y) := x/y$$

Examples: • f(1,1) = 1



$$f(x,y) := x/y$$

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Examples: • f(1,1) = 1 = f(2,2)



$$f(x,y) := x/y$$

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2/17



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- f(1,1) = 1 = f(2,2)
- $f(1,2) = \frac{1}{2}$
- f(2,1) = 2

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Claim

Now you know long division.

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f(x, y) = x/y is the uniquely determined by the above,

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Claim

Now you know long division.

Proof.

f(x, y) = x/y is the uniquely determined by the above, as a function of the form f(x, y) = (ax + b)/(cy + d).

Theme



Simple functions are essentially determined by sufficiently many random samples.

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Example

• PAC (Probably Approximately Correct) learning

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- PAC (Probably Approximately Correct) learning
- Error-correcting Codes

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- (Black-box) Polynomial Identity Testing (PIT) given an algebraic circuit *C*

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- PAC (Probably Approximately Correct) learning
- Error-correcting Codes
- (Black-box) Polynomial Identity Testing (PIT) given an algebraic circuit C, does the polynomial C(x) equal zero?

More on the Theme

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determined by random

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Simple functions are essentially **efficiently** determined by random samples.



Simple functions are essentially **efficiently** determined by **deterministic** samples.

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Example (of hope)

• Coding theory:

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Example (of hope)

• Coding theory: need **deterministic** coding schemes for communication

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- Coding theory: need **deterministic** coding schemes for communication
- Complexity theory: understanding the power of (pseudo)randomness
- Complexity theory: connections with circuit lower bounds

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Bilinear Forms

Let ${\mathbb F}$ be a field.

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Bilinear Forms



Bilinear Forms

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$$f(\vec{x},\vec{y}) := \vec{x}^t M \vec{y}$$

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Answer

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Let \mathbb{F} be a field. Let M be an $n \times n$ matrix

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Question

Can we construct $\approx 2nr$ (resp. 4nr) **explicit** samples for identity testing (resp. learning)?

Results

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Definition

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Results

Definition

Let $\vec{x} \in \mathbb{F}^n$ be an unknown vector.



Definition

Let $\vec{x} \in \mathbb{F}^n$ be an unknown vector. A measurement of \vec{x}


Results

Definition

Let $\vec{x} \in \mathbb{F}^n$ be an unknown vector. A **measurement of** \vec{x} is an inner product $\langle \vec{a}, \vec{x} \rangle$ for some known vector $\vec{a} \in \mathbb{F}^n$.

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Thus, evaluations to the bilinear form $f(\vec{x}, \vec{y}) = \vec{x}^t M \vec{y} = \langle \vec{x}^t \vec{y}, M \rangle$ are all rank-1 measurements of M.

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Over large fields, one can efficiently learn an $n \times n$ matrix of rank $\leq r$ with 4nr measurements and can even be done with rank-1 measurements.

The number of measurements is optimal over algebraically closed fields. The use of rank-1 measurements is novel, and thus instantiates the meta-hope, by learning a function from deterministic evaluations.

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Definition (Tensor)

• A tensor is a higher dimensional matrix in $[n]^d$.

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This is the *first* deterministic sub-exponential time algorithm for even determining if the d-linear form is non-zero, by only using its evaluations.

Any r-sparse-recovery oracle with measurements $\mathcal V$

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Any r-sparse-recovery oracle with measurements \mathcal{V} can be turned into a rank \leq r low-rank recovery algorithm, with measurements \mathcal{H}

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An *r*-sparse-recovery oracle is simply an error-correcting-code with that can correct r errors (thus, distance 2r)

 \implies take the Reed-Solomon code with 2r measurements (for large fields).

 \implies get $2n \cdot 2r = 4nr$ measurements

rank 1 measurements: do a clever change of basis from \mathcal{H} to \mathcal{H}'

Sparsity and Rank (I)

want: *M* has rank $\leq r$

want: *M* has rank $\leq r \implies$ related *r* sparse vector.

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Definition

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Let *M* be $n \times n$.

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Let *M* be $n \times n$, of rank $\leq r$.

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Lemma

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The rows with non-zeros amongst the entries a, b, c, d, eare linearly independent, as this is a triangular system, so this follows from standard linear algebra. So if the rank is at most 3,

Lemma

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Proof by example.



The rows with non-zeros amongst the entries a, b, c, d, eare linearly independent, as this is a triangular system, so this follows from standard linear algebra. So if the rank is at most 3, then this diagonal is 3-sparse.

Learning an 7×7 , rank ≤ 3 matrix, essentially using 3-sparse recovery:

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Learning an 7 \times 7, rank \leq 3 matrix, essentially using 3-sparse recovery:

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Learning an 7×7 , rank ≤ 3 matrix, essentially using 3-sparse recovery:



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Learning an 7×7 , rank ≤ 3 matrix, essentially using 3-sparse recovery:

0	0	0	0	0	0	0		
0	0	0	1	1	1	1		
0	0	1	1	0	0	1		
0	1	1	1	0	1	1		
0	1	2	3	1	2	3		
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0	1	2	3	1	2	3		
Γ0	0	0	0	0		0	07	
Г0 0	0 0	0 0	0 1	0 1		0 1	0 1	
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0 0 0 0	0 0 1 0	0 0 1 0	0 1 0 0	0 1 0 0	L	0 1 -1 1 0	0 1 0 0 0	()
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Learning an 7×7 , rank ≤ 3 matrix, essentially using 3-sparse recovery:

0	0	0	0	0	0	0	
0	0	0	1	1	1	1	
0	0	1	1	0	0	1	
0	1	1	1	0	1	1	
0	1	2	3	1	2	3	
0	1	2	3	1	2	3	
0	1	2	3	1	2	3	
Γ0	0	0	0	0		0	07
ГО 0	0 0	0 0	0 1	0 1		0 1	0 1
0 0 0	0 0 0	0 0 1	0 1 0	0 1 	1	0 1 -1	0 1 0
0 0 0	0 0 0 1	0 0 1 0	0 1 0 0	0 1 	1	$0 \\ 1 \\ -1 \\ 1$	0 1 0 0
0 0 0 0	0 0 1 0	0 0 1 0	0 1 0 0	0 1 0 0	1	0 1 -1 1 0	0 1 0 0 0
0 0 0 0 0	0 0 1 0	0 0 1 0 0	0 1 0 0 0	0 1 	1	$0\\1\\-1\\0\\0$	0 1 0 0 0 0
0 0 0 0 0 0	0 0 1 0 0 0	0 0 1 0 0 0	0 1 0 0 0 0	0 1 	1	$egin{array}{c} 0 \\ 1 \\ -1 \\ 0 \\ 0 \\ 0 \\ 0 \end{array}$	0 1 0 0 0 0 0

0	0	0	0	0	0	0
0	0	0	1	1	1	1
0	0	1	0	-1	-1	0
0	1	0	0	0	1	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	?
	0 0 0 0 0 0	0 0 0 0 0 0 0 1 0 0 0 0 0 0	0 0 0 0 0 0 1 0 1 0 1 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 1 1 0 0 1 0 -1 0 1 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$

Learning an 7×7 , rank ≤ 3 matrix, essentially using 3-sparse recovery:

[0]	0	0	0	0	0	07	
0	0	0	1	1	1	1	
0	0	1	1	0	0	1	
0	1	1	1	0	1	1	
0	1	2	3	1	2	3	
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ГО 0	0 0	0 0	0 1	0 1		0 1	0 1
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0 0 0 0	0 0 0 1	0 0 1 0	0 1 0 0	0 1 	1	$0 \\ 1 \\ -1 \\ 1$	0 1 0 0
0 0 0 0	0 0 1 0	0 0 1 0	0 1 0 0	0 1 	1	0 1 -1 1 0	0 1 0 0 0
0 0 0 0 0	0 0 1 0 0	0 0 1 0 0	0 1 0 0 0	0 1 	1	$0 \\ 1 \\ -1 \\ 1 \\ 0 \\ 0 \\ 0$	0 1 0 0 0 0
0 0 0 0 0 0	0 0 1 0 0 0	0 0 1 0 0 0	0 1 0 0 0 0	0 1 	1	$egin{array}{c} 0 \\ 1 \\ -1 \\ 0 \\ 0 \\ 0 \\ 0 \end{array}$	0 1 0 0 0 0 0

0	0	0	0	0	0	0
0	0	0	1	1	1	1
0	0	1	0	-1	-1	0
0	1	0	0	0	1	0
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0	1	2	3	1	2	3	
Γ0	0	0	0	0		0	0
ГО 0	0 0	0 0	0 1	0 1		0 1	0 [.] 1
0 0 0	0 0 0	0 0 1	0 1 0	0 1 	1	0 1 -1	0 1 0
0 0 0 0	0 0 0 1	0 0 1 0	0 1 0 0	0 1 	1	$0 \\ 1 \\ -1 \\ 1$	0 [.] 1 0 0
ГО О О О	0 0 0 1 0	0 0 1 0 0	0 1 0 0	0 1 0 0	1	0 1 -1 1 0	0 ⁻ 1 0 0
0 0 0 0 0	0 0 1 0 0	0 0 1 0 0	0 1 0 0 0	0 1 -: 0 0 0	1	$0 \\ 1 \\ -1 \\ 1 \\ 0 \\ 0 \\ 0$	0 ⁻ 1 0 0 0

٢0	0	0	0	0	0	0]
0	0	0	1	1	1	1
0	0	1	1	0	0	1
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0	1	2	3	1	2	3
0	1	2	3	1	2	3

Proof of Low-Rank Recovery (cont'd)

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Proof of Low-Rank Recovery (cont'd)

Theorem

Any r-sparse-recovery oracle with measurements \mathcal{V} can be turned into a rank \leq r low-rank recovery algorithm, with measurements \mathcal{H} , and $|\mathcal{H}| = 2n|\mathcal{V}|$.

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Proof.

• M rank $\leq r$

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Proof.

• M rank $\leq r \implies$ the first non-zero diagonal is *r*-sparse

Any r-sparse-recovery oracle with measurements \mathcal{V} can be turned into a rank \leq r low-rank recovery algorithm, with measurements \mathcal{H} , and $|\mathcal{H}| = 2n|\mathcal{V}|$.

- M rank $\leq r \implies$ the first non-zero diagonal is *r*-sparse
- $M \operatorname{rank} \leq r$,

Any r-sparse-recovery oracle with measurements \mathcal{V} can be turned into a rank \leq r low-rank recovery algorithm, with measurements \mathcal{H} , and $|\mathcal{H}| = 2n|\mathcal{V}|$.

- M rank $\leq r \implies$ the first non-zero diagonal is *r*-sparse
- M rank $\leq r$, reduced row-echelon form

Any r-sparse-recovery oracle with measurements \mathcal{V} can be turned into a rank \leq r low-rank recovery algorithm, with measurements \mathcal{H} , and $|\mathcal{H}| = 2n|\mathcal{V}|$.

- $M \operatorname{rank} \leq r \implies$ the first non-zero diagonal is *r*-sparse
- *M* rank \leq *r*, reduced row-echelon form \implies every diagonal is *r*-sparse

Any r-sparse-recovery oracle with measurements \mathcal{V} can be turned into a rank \leq r low-rank recovery algorithm, with measurements \mathcal{H} , and $|\mathcal{H}| = 2n|\mathcal{V}|$.

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- *M* rank \leq *r*, reduced row-echelon form \implies every diagonal is *r*-sparse
- M rank $\leq r$, first k diagonals in reduced row-echelon form

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- *M* rank \leq *r*, reduced row-echelon form \implies every diagonal is *r*-sparse
- M rank $\leq r$, first k diagonals in reduced row-echelon form \implies (k + 1)-diagonal of M is essentially r-sparse

Any r-sparse-recovery oracle with measurements \mathcal{V} can be turned into a rank \leq r low-rank recovery algorithm, with measurements \mathcal{H} , and $|\mathcal{H}| = 2n|\mathcal{V}|$.

- $M \operatorname{rank} \leq r \implies$ the first non-zero diagonal is *r*-sparse
- *M* rank \leq *r*, reduced row-echelon form \implies every diagonal is *r*-sparse
- M rank ≤ r, first k diagonals in reduced row-echelon form ⇒
 (k + 1)-diagonal of M is essentially r-sparse (and actually 2r-sparse)

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- learning *M* via iteratively learning diagonals and row reducing (downward)

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- undo row-reduction at the end

Any r-sparse-recovery oracle with measurements \mathcal{V} can be turned into a rank \leq r low-rank recovery algorithm, with measurements \mathcal{H} , and $|\mathcal{H}| = 2n|\mathcal{V}|$.

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 (k + 1)-diagonal of M is essentially r-sparse (and actually 2r-sparse)
- learning *M* via iteratively learning diagonals and row reducing (downward)
- undo row-reduction at the end
- called sparse-recovery 2n times once per diagonal

Summary

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• Low-rank recovery of matrices is reducible to sparse recovery of vectors.

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- There is a deterministic quasi-polynomial-time algorithm for learning low-rank tensors.

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Open Questions:

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Open Questions:

• Can our reduction from low-rank recovery to sparse recovery be made stable?

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- There is a deterministic quasi-polynomial-time algorithm for learning low-rank tensors.

Open Questions:

- Can our reduction from low-rank recovery to sparse recovery be made stable?
- Deterministic *polynomial*-time algorithm for learning tensors?

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